WEIDMANN

AVOIDING CATASTROPHIC FAILURES DUE TO SHORT CIRCUIT EVENTS IN POWER TRANSFORMERS STEFAN JAUFER

ALTERTA

DISCLAIMER

Nothing contained herein shall be construed as a representation that any recommendations, use or resale of the product or process described herein is permitted and complies with the rules or regulations of any countries, regions, localities, etc., or does not infringe upon patents or other intellectual property rights of third parties.

The information provided herein is based on data Weidmann Electrical Technology believes to be reliable, to the best of its knowledge and is provided at the request of and without charge to those who requested to join our webinar. Accordingly, Weidmann Electrical Technology does not guarantee or warrant such information and assumes no liability for its use. This document is subject to change without further notice.

All rights reserved. This presentation and its content are protected by copyright laws. Unauthorised use or reproduction of any part of this presentation without prior written permission is strictly prohibited.



Introduction

1

2

3

4

5

Sensor Generation 3

Beta Test

In Service Measurements

Summary

INTRODUCTION

TASKS OF TRANSFORMER IN THE NETWORK

- Change system voltage
 - Reduction of transmission losses by using HV, UHV, EHV
- Galvanic separation of grids
 - Different grounding strategies (solidly earthed, compensated, isolated neutral system,...)
- Reduction of short circuit currents
 - Short circuit impedance
 - Distribution transformers: 4-6 %
 - SMPT: 6-12 %
 - Large power transformers: 9-16 %
- \rightarrow High currents
 - Function of transformer must be guaranteed during short circuit events
 - Key component in transmission
 - Reliable but expensive component



FIGURE 11: PERCENTAGE OF PRIMARY LOCATION OF DISTURBANCE FOR 220 KV AND 380 KV

Source: CIGRE TB 642



INTRODUCTION FORCES INSIDE (SINGLE) WINDING

Lorenz Forces: Current and resulting magnetic field makes:

- Compression of the winding in axial direction
- Expansion forces in radial direction



INTRODUCTION FORCES BETWEEN WINDINGS



Source: electrical-engineering-portal.com





INTRODUCTION CLAMPING BEHAVIOR



Interactions

- Tie plates
 - Close to the core or outside
 - Stray field
 - Loosen tightening
- Wire
 - Heated by load
 - Tilting of wires
- Insulation
 - Moisture depending swelling/shrinking
 - Viscoelastic and -plastic behavior
 - Aging

FUNDAMENTAL STATEMENTS



Tight clamping is required for reliable operation

Keep conductor and windings at designed positions/locations

Clamping forces/pressure designed to transformer type

Deviation due to fabrication reality vs. design

Clamping pressure is dynamic



Introduction

Sensor Generation 3

Beta Test

3

4

5

In Service Measurements

Summary



REQUIREMENTS FOR DESIGN



Ambient inside transformer and during fabrication

Immunity to magnetic fields

Immunity to dielectric stress

Mechanical strength

Distant evaluation of signals

CLAMPING FORCE SENSOR

SENSING PRINCIPLE: FIBER BRAGG GRATING

Transmitted

λ

λ

Input

- Single mode fiber
- Periodical changes in core refraction index

→Interference filter

λ

Reflected

- Reflected/transmitted signal depending on distance
 between disturbance
- Intensity depending on number of disturbance
- By changing mechanical tension on fiber
 - Change of length/distance between disturbance
 - \rightarrow Change of optical signal: wavelength

Source: de.wikipedia.org/wiki/Faser-Bragg-Gitte

CLAMPING FORCE SENSOR WORKING PRINCIPLE

Dielectric Fiber Bragg Load Cell:

- Clamping pressure creates strain at one grating of the fiber
- Wavelength change of reflected light is proportional to the strain
- Temperature change creates thermal expansion and tension on grating
- Second grading is used for temperature measurement and compensation
- Bottom and cover plates are used to adjust the height according to the other spacers

CLAMPING FORCE SENSOR GEN 3 SENSOR FABRICATION

- Sensor size example 165x75 mm
- Sensing element in middle of sensor
- Nominal load $\leq 10 \frac{N}{mm^2}$
- Break load $\geq 35 \frac{N}{mm^2}$

SENSOR SPECIFICATION SENSOR SIZE

- Minimum size 52 x 9 mm (Load and temperature sensor, tube fixation)
- Load sensing element 12x9 mm
- Width increments 10 mm (9 mm +1 mm gap)
- Length increments 53 mm (52 mm +1 mm gap)
- Height 21 mm (20 mm + 2 x 0.5 mm) recommended to use 2 x 2 mm Nomex® board as load distributor
- Nominal load $\leq 10 \frac{N}{mm^2}$
- Break load $\geq 35 \frac{N}{mm^2}$

CLAMPING FORCE SENSOR SPECIFICATION

Measuring range: 0...10 N/mm² Accuracy: ± 10 % Operating Temperature: -40...140 °C

Mineral oil compatibility Compression: <35 MPa / 5000 psi AC field strength without PD: > 6 kV/mm

Introduction

Sensor Generation 3

Beta Test

2

3

4

5

In Service Measurements

Summary

BETA TEST DYNALOAD PROJECT BACKGROUND

Part of the DynaLoad research project

 Partners: SINTEF Energy, ELVIA, Kolektor ETRA, Weidmann, Statnett SF, Statkraft SF, EDF, SP Energy Networks, Siemens Energy

Main goal:

 "To characterize the long-term mechanical endurance of transformer insulation under heavy dynamic loading conditions"

Installation

- Substation Rade, near Oslo (NO)
- Light industry, urban, rural
- Two (2) Transformers 40 MVA (3ph), ONAN 132 kV
- Commissioned in Q4/2020
- Installation of eight (8) x F-sensors at the middle limb of one transformer
- Possibility to switch on/off the xfrm (n-1)

BETA TEST DYNALOAD PROJECT INSTALLATION AT THE MIDDLE LIMB OF THE TRANSFORMER

Courtesy: Kolektor ETRA

BETA TEST DYNALOAD PROJECT

MONITORING OF THE CLAMPING FORCES DURING THE HEAT RUN TEST

Transformer during Heat Run Test

Courtesy: Kolektor ETRA

WIA – The Winding Integrity Analyzer

IN FIELD INSTALLATION

SENSORS ON TRANSFORMER

Source: ARWtr 2022

22

HEAT RUN TEST CHANGE OF CLAMPING PRESSURE DURING THE TEST

HEAT RUN TEST

CHANGE OF CLAMPING PRESSURE DURING THE TEST - CONTINUING

HEAT RUN TEST

CHANGE OF CLAMPING PRESSURE, FIRST TWO (2) MIN

Courtesy: DynaLoad project

HEAT RUN TEST

CHANGE OF CLAMPING PRESSURE BEFORE, DURING AND AFTER THE TEST

Introduction

Sensor Generation 3

Beta Test

In Service Measurements

Summary

STEP TEST – OVERVIEW

Copyright © Weidmann Electrical Technology 2023

STEP TEST – CLOSER VIEW

STEP TEST – STEP UP/STEP DOWN (FIRST PERIOD)

STEP TEST – BACK TO NORMAL OPERATION

Introduction

Sensor Generation 3

Beta Test

In Service Measurements

Summary

4

Tight clamping is required for reliable operation

Clamping is temperature related and will change over time

Sensors for clamping measurement available

Small changes are detectable

Interpretation of the clamping force records requires expertise and experience

Monitoring of clamping force to improve transformer reliability

QUESTIONS?

00

.....

11

STEFAN.JAUFER@WEIDMANN-GROUP.COM

ADDITIONAL SOURCES

• DynaLoad:

- <u>https://www.sintef.no/en/projects/2021/dynaload-dynamic-loading-of-transformer-insulation/</u>
- <u>https://prosjektbanken.forskningsradet.no/project/FORISS/319289</u>
- Cigre TB642
 - "Transformer reliability survey", 2015, WG A2.37, <u>https://e-cigre.org/publication/642-transformer-reliability-survey</u>
- ARWtr 2022
 - Inge MADSHAVEN et al.: "On-line Direct Clamping Pressure Monitoring of Power Transformer Windings", 7th International Advanced Research Workshop on transformers, 24-26th Oct. 2022, Baiona Spain, Paper 2.10
 - https://ieeexplore.ieee.org/document/9959909

